ADVANCED PLACEMENT PHYSICS C EQUATIONS

MECHANICS

$v_x = v_{x0} + a_x t$

$x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$

$v_x^2 = {v_{x0}}^2 + 2a_x (x - x_0)$

$\vec{a} = \frac{\sum \vec{F}}{m} = \frac{\vec{F}_{net}}{m}$

$\vec{F} = \frac{d\vec{p}}{dt}$

$\vec{J} = \int \vec{F}\, dt = \Delta\vec{p}$

$\vec{p} = m\vec{v}$

$\left|\vec{F}_f\right| \le \mu \left|\vec{F}_N\right|$

$\Delta E = W = \int \vec{F} \bullet d\vec{r}$

$K = \frac{1}{2} m v^2$

$P = \frac{dE}{dt}$

$P = \vec{F} \bullet \vec{v}$

$\Delta U_g = mg\Delta h$

$a_c = \frac{v^2}{r} = \omega^2 r$

$\vec{\tau} = \vec{r} \times \vec{F}$

$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$

$I = \int r^2 dm = \sum m r^2$

$x_{cm} = \frac{\sum m_i x_i}{\sum m_i}$

$v = r\omega$

$\vec{L} = \vec{r} \times \vec{p} = I\vec{\omega}$

$K = \frac{1}{2} I \omega^2$

$\omega = \omega_0 + \alpha t$

$\theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2$

a = acceleration
E = energy
F = force
f = frequency
h = height
I = rotational inertia
J = impulse
K = kinetic energy
k = spring constant
ℓ = length
L = angular momentum
m = mass
P = power
p = momentum
r = radius or distance
T = period
t = time
U = potential energy
v = velocity or speed
W = work done on a system
x = position
μ = coefficient of friction
θ = angle
τ = torque
ω = angular speed
α = angular acceleration
ϕ = phase angle

$\vec{F}_s = -k\Delta\vec{x}$

$U_s = \frac{1}{2} k (\Delta x)^2$

$x = x_{\max} \cos(\omega t + \phi)$

$T = \frac{2\pi}{\omega} = \frac{1}{f}$

$T_s = 2\pi\sqrt{\frac{m}{k}}$

$T_p = 2\pi\sqrt{\frac{\ell}{g}}$

$\left|\vec{F}_G\right| = \frac{G m_1 m_2}{r^2}$

$U_G = -\frac{G m_1 m_2}{r}$

ELECTRICITY AND MAGNETISM

$\left|\vec{F}_E\right| = \frac{1}{4\pi\varepsilon_0} \left|\frac{q_1 q_2}{r^2}\right|$

$\vec{E} = \frac{\vec{F}_E}{q}$

$\oint \vec{E} \bullet d\vec{A} = \frac{Q}{\varepsilon_0}$

$E_x = -\frac{dV}{dx}$

$\Delta V = -\int \vec{E} \bullet d\vec{r}$

$V = \frac{1}{4\pi\varepsilon_0} \sum_i \frac{q_i}{r_i}$

$U_E = qV = \frac{1}{4\pi\varepsilon_0} \frac{q_1 q_2}{r}$

$\Delta V = \frac{Q}{C}$

$C = \frac{\kappa \varepsilon_0 A}{d}$

$C_p = \sum_i C_i$

$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$

$I = \frac{dQ}{dt}$

$U_C = \frac{1}{2} Q \Delta V = \frac{1}{2} C (\Delta V)^2$

$R = \frac{\rho \ell}{A}$

$\vec{E} = \rho \vec{J}$

$I = Nev_d A$

$I = \frac{\Delta V}{R}$

$R_s = \sum_i R_i$

$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$

$P = I\Delta V$

A = area
B = magnetic field
C = capacitance
d = distance
E = electric field
ε = emf
F = force
I = current
J = current density
L = inductance
ℓ = length
n = number of loops of wire per unit length
N = number of charge carriers per unit volume
P = power
Q = charge
q = point charge
R = resistance
r = radius or distance
t = time
U = potential or stored energy
V = electric potential
v = velocity or speed
ρ = resistivity
Φ = flux
κ = dielectric constant

$\vec{F}_M = q\vec{v} \times \vec{B}$

$\oint \vec{B} \bullet d\vec{\ell} = \mu_0 I$

$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I\, d\vec{\ell} \times \hat{r}}{r^2}$

$\vec{F} = \int I\, d\vec{\ell} \times \vec{B}$

$B_s = \mu_0 n I$

$\Phi_B = \int \vec{B} \bullet d\vec{A}$

$\varepsilon = \oint \vec{E} \bullet d\vec{\ell} = -\frac{d\Phi_B}{dt}$

$\varepsilon = -L\frac{dI}{dt}$

$U_L = \frac{1}{2} L I^2$

ADVANCED PLACEMENT PHYSICS C EQUATIONS

GEOMETRY AND TRIGONOMETRY

Rectangle

$A = bh$

Triangle

$A = \frac{1}{2}bh$

Circle

$A = \pi r^2$

$C = 2\pi r$

$s = r\theta$

Rectangular Solid

$V = \ell wh$

Cylinder

$V = \pi r^2 \ell$

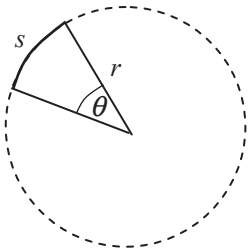
$S = 2\pi r\ell + 2\pi r^2$

Sphere

$V = \frac{4}{3}\pi r^3$

$S = 4\pi r^2$

A = area
C = circumference
V = volume
S = surface area
b = base
h = height
ℓ = length
w = width
r = radius
s = arc length
θ = angle



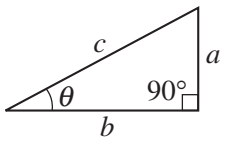
Right Triangle

$a^2 + b^2 = c^2$

$\sin\theta = \frac{a}{c}$

$\cos\theta = \frac{b}{c}$

$\tan\theta = \frac{a}{b}$



CALCULUS

$$\frac{df}{dx} = \frac{df}{du}\frac{du}{dx}$$

$$\frac{d}{dx}\left(x^n\right) = nx^{n-1}$$

$$\frac{d}{dx}\left(e^{ax}\right) = ae^{ax}$$

$$\frac{d}{dx}(\ln ax) = \frac{1}{x}$$

$$\frac{d}{dx}[\sin(ax)] = a\cos(ax)$$

$$\frac{d}{dx}[\cos(ax)] = -a\sin(ax)$$

$$\int x^n dx = \frac{1}{n+1}x^{n+1},\ n \neq -1$$

$$\int e^{ax} dx = \frac{1}{a}e^{ax}$$

$$\int \frac{dx}{x+a} = \ln|x+a|$$

$$\int \cos(ax)dx = \frac{1}{a}\sin(ax)$$

$$\int \sin(ax)dx = -\frac{1}{a}\cos(ax)$$

VECTOR PRODUCTS

$$\vec{A}\bullet\vec{B} = AB\cos\theta$$

$$\left|\vec{A}\times\vec{B}\right| = AB\sin\theta$$